

Solitary wave solutions of a generalized schrödinger equation with kerr nonlinearity

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ABSTRACT

This study investigates a generalized Schrödinger equation that governs the propagation of optical pulses in nonlinear media in the presence of Kerr nonlinearity. Using Kudryashov’s generalized method, we reduce the model to a Duffing-type ordinary differential equation whose first integral yields an exact bright-soliton solution. We validate this solution in three complementary ways. The admissible parameter regime is stated explicitly, and the values used in every figure are shown to fall within this regime, ensuring that the plotted solutions are real and physically meaningful. The solution is then recovered via a stable boundary-value integration of the reduced equation, which agrees with the closed form to $R^2 = 1.0000$ and a root-mean-square error of order 10^{-11} . Finally, the dependence of the wave on the Kerr coefficient is characterised quantitatively: rank-correlation analysis reveals that the peak amplitude is a perfectly monotone but nonlinear function of the Kerr coefficient (Spearman $\rho = -1$, Kendall $\tau = -1$, Pearson $r = -0.94$) obeying the exact law $|A|_{\max} \propto N^{-1/2}$, while the characteristic width is proved to be independent of it. Cramér-von Mises and Anderson–Darling goodness-of-fit tests, together with a cumulative-distribution-function outlier screening, confirm that the numerical samples are statistically consistent with the theoretical model and free of artefacts. A phase-plane portrait, a propagation map and a two-parameter amplitude map further clarify the dynamics. All computations were reproduced in a license-free open-source environment to ensure portability and reproducibility.



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1. Introduction

Many phenomena across various fields of applied science are governed by nonlinear partial differential equations (NLPDEs).^{1–5} These equations arise in nonlinear optics, plasma physics, fluid dynamics, and condensed-matter theory, describing behaviours that no linear model can reproduce; recent studies of the Hirota–Maccari system³ and improved analytical techniques with chaos-detection tools⁵ illustrate the richness of the resulting dynamics. Among the solutions of NLPDEs, solitary waves are of particular interest due to their remarkable stability: they retain their shape and speed even after interaction. Their construction is central to understanding the intrinsic dynamics of nonlinear systems and sheds light on the physical mechanisms underlying observed phenomena. Over the past two decades several effective techniques have been developed for this purpose, including the ansatz method,^{6–8} the exponential method,^{9–11} and other approaches.^{12–15}

The present study examines the following generalized Schrödinger equation (gSE)¹⁶

$$\iota \frac{\partial \mathcal{A}}{\partial y} + \frac{1}{2} \left(\frac{\partial^2 \mathcal{A}}{\partial x^2} + \frac{\partial^2 \mathcal{A}}{\partial z^2} - \frac{\partial^2 \mathcal{A}}{\partial t^2} \right) + \aleph |\mathcal{A}|^2 \mathcal{A} = 0, \quad (1)$$

which describes the propagation of optical pulses in nonlinear media. Here $\mathcal{A}(x, y, z, t)$ is the complex envelope, y is the evolution (propagation) variable, the mixed-signature operator $\partial_{xx} + \partial_{zz} - \partial_{tt}$ encodes the balance between transverse diffraction and anomalous temporal dispersion, and $\aleph$ is the Kerr coefficient. This model has attracted recent attention. Kumar *et al.*¹⁷ analysed it via Lie symmetry analysis, reducing the governing equation and constructing a range of soliton-type solutions. Hosseini *et al.*¹⁸ carried out a detailed dynamical study of the gSE, covering bifurcation, chaotic behaviour and sensitivity to initial conditions, and derived soliton solutions describing its nonlinear wave structures.

In 2022, a well-structured analytical method,¹⁹ introduced by N. A. Kudryashov, was used to obtain solitary-wave solutions for a class of nonlinear Schrödinger equations. Hosseini and colleagues later confirmed its versatility on various NLPDEs, including coupled nonlinear Schrödinger equations,²⁰ the Konno–Oono equation,²¹ unstable Schrödinger equations,²² and Ginzburg–Landau equations.²³ Nevertheless, to the best of our knowledge, the generalized Schrödinger equation with Kerr nonlinearity in the form (1) has not been treated by this method.

It is important to position the present contribution precisely relative to the most closely related

recent work. Yasin *et al.*²⁴ studied a generalized higher-order nonlinear Schrödinger equation of cubic–quintic type,

$$\iota q_x - \frac{\beta_2}{2} q_{tt} + \alpha_1 |q|^2 q - \iota \frac{\beta_3}{6} q_{ttt} - \frac{\beta_4}{24} q_{tttt} + \alpha_2 |q|^4 q = 0, \quad (2)$$

in a single spatial dimension, applying the modified exponential rational function method to obtain multi-peak solitons and breather-type solutions, along with a conservation-law derivation and linear-stability analysis. Although both works belong to the nonlinear Schrödinger family, they differ in ways that are mathematically substantive and establish the novelty of the present study. (i) **Equation (2)** is (1+1)-dimensional with a single elliptic spatial derivative, whereas (1) is (3+1)-dimensional with the mixed-signature operator $\partial_{xx} + \partial_{zz} - \partial_{tt}$; the reduction of (1) therefore depends on the indefinite quadratic form $\alpha_1^2 + \gamma_1^2 - \theta_1^2$, whose sign controls the existence of a localized solution and has no analogue in (2). (ii) The cubic–quintic terms $\alpha_1 |q|^2 q + \alpha_2 |q|^4 q$ and the third- and fourth-order dispersion β_3, β_4 lead, after reduction, to a fourth-order ordinary differential equation with a sextic effective potential, whereas the pure Kerr law in (1) yields a second-order Duffing-type equation with a quartic potential, so that the balance number here is $N = 1$ rather than the larger value forced by the quintic term. (iii) The multi-peak and breather structures of²⁴ arise from competition between quintic nonlinearity and higher-order dispersion; the present model supports a single-hump bright soliton obtained in closed form through Kudryashov’s integral reduction, whose amplitude follows the exact power law $|\mathcal{A}|_{\max} \propto \aleph^{-1/2}$ derived below. (iv) Reference²⁴ uses the modified exponential rational function method, an ansatz-expansion technique, whereas we use Kudryashov’s generalized method, which reduces the problem to a first-order auxiliary equation integrated in quadrature and does not require an integer balance number. In short, the present study is not a re-parameterisation of:²⁴ it treats a structurally different (higher-dimensional, indefinite-operator, pure-Kerr) equation with a different reduction, obtains a different class of solutions, and adds a quantitative statistical validation that²⁴ did not report.

The principal novelty of this work therefore lies in (a) the first application of Kudryashov’s generalized method to the (3+1)-dimensional generalized Schrödinger equation with Kerr nonlinearity; (b) an explicit statement of the admissible parameter regime, with a demonstration that the

reported solutions are real and physically meaningful with it; and (c) a quantitative, reproducible characterisation of the soliton dynamics, including an amplitude-scaling law, correlation analysis, goodness-of-fit testing, and outlier screening, supported by a phase-plane and parameter-map study, all of which move the analysis well beyond visual inspection of the plots.

The remainder of the paper is organized as follows. Section 2 gives a self-contained account of Kudryashov's generalized method. Section 3 reduces the governing model and constructs its solitary-wave solution, with every step derived explicitly. Section 4 examines the influence of Kerr nonlinearity on the dynamics of the solitary wave under suitable parameter regimes, supported by two- and three-dimensional visualizations and by quantitative statistical validation. Section 5 concludes.

2. Kudryashov's generalized method

This section presents a self-contained account of Kudryashov's generalized method,^{19–21} together with the conditions under which each transformation is valid. Suppose that, under a travelling-wave reduction, the governing model (1) can be written as a first-order autonomous ordinary differential equation of the form

$$\mathcal{B}_\delta^2 = \Phi(\mathcal{B}) \Psi(\mathcal{B}), \quad \mathcal{B} = \mathcal{B}(\delta), \quad (3)$$

where Φ and Ψ are polynomials in $\mathcal{B}$ and the right-hand side is non-negative on the relevant interval, so that $\mathcal{B}_\delta$ is real. Such a first-order form always exists for the conservative second-order equations considered here: multiplying an equation of the type $\mathcal{B}_{\delta\delta} = F(\mathcal{B})$ by $\mathcal{B}_\delta$ and integrating once yields precisely the energy relation (3).

The method integrates (3) by splitting it into two solvable sub-problems through an auxiliary independent variable ζ . Introduce

$$\mathcal{B}(\delta) = \mathcal{M}(\zeta), \quad \zeta = \Omega(\delta), \quad (4)$$

where Ω is taken to be monotone, hence invertible, so that the correspondence between δ and ζ is one-to-one. Applying the chain rule to (4) gives

$$\mathcal{B}_\delta = \mathcal{M}_\zeta \zeta_\delta. \quad (5)$$

Substituting (4) and (5) into (3) yields

$$\mathcal{M}_\zeta^2 \zeta_\delta^2 = \Phi(\mathcal{M}) \Psi(\mathcal{M}). \quad (6)$$

The key step is to assign the factor Φ to the auxiliary variable by imposing

$$\zeta_\delta^2 = \Phi(\mathcal{M}), \quad (7)$$

which is admissible precisely when $\Phi(\mathcal{M}) \geq 0$ over the range of $\mathcal{M}$; this choice fixes the map Ω through the quadrature (9) below. With (7) in

force, **Equation (6)** decouples into the amplitude equation

$$\mathcal{M}_\zeta^2 = \Psi(\mathcal{M}), \quad (8)$$

whose right-hand side must likewise be non negative for $\mathcal{M}_\zeta$ to be real. The original variable is then recovered from

$$\delta = \delta_0 + \int \frac{d\zeta}{\sqrt{\Phi(\mathcal{M})}}. \quad (9)$$

Equation (8) is a standard first-order separable equation with a known closed-form solution for polynomial Ψ ; substituting that solution into the quadrature (9) and inverting the resulting relation produces the solitary-wave solution of (3). A useful feature of the decomposition (7)–(9) is that the balance number entering $\mathcal{M}(\zeta)$ need not be an integer, which broadens the applicability of the procedure relative to expansion methods that require an integer truncation order.²³

3. Generalized schrödinger equation and its solitary-wave solution

We now apply the method of Section 2 to the governing **Equation (1)**. To obtain its reduced form, introduce the complex travelling-wave transformation¹⁸

$$\mathcal{A}(x, y, z, t) = \mathcal{B}(\delta) e^{\iota(\alpha_2 x + \beta_2 y + \gamma_2 z - \theta_2 t)}, \quad \delta = \alpha_1 x + \beta_1 y + \gamma_1 z - \theta_1 t, \quad (10)$$

where $\mathcal{B}(\delta)$ is a real amplitude, θ_1 is the wave velocity and θ_2 the wave frequency. Writing $\psi = \alpha_2 x + \beta_2 y + \gamma_2 z - \theta_2 t$, the required derivatives are

$$\begin{aligned} \iota \mathcal{A}_y &= (\iota \beta_1 \mathcal{B}_\delta - \beta_2 \mathcal{B}) e^{\iota\psi}, \\ \mathcal{A}_{xx} &= (\alpha_1^2 \mathcal{B}_{\delta\delta} + 2\iota \alpha_1 \alpha_2 \mathcal{B}_\delta - \alpha_2^2 \mathcal{B}) e^{\iota\psi}, \\ \mathcal{A}_{zz} &= (\gamma_1^2 \mathcal{B}_{\delta\delta} + 2\iota \gamma_1 \gamma_2 \mathcal{B}_\delta - \gamma_2^2 \mathcal{B}) e^{\iota\psi}, \\ \mathcal{A}_{tt} &= (\theta_1^2 \mathcal{B}_{\delta\delta} + 2\iota \theta_1 \theta_2 \mathcal{B}_\delta - \theta_2^2 \mathcal{B}) e^{\iota\psi}. \end{aligned} \quad (11)$$

Substituting (11) into (1), using $|\mathcal{A}|^2 \mathcal{A} = \mathcal{B}^3 e^{\iota\psi}$, dividing through by $e^{\iota\psi}$ and separating the real and imaginary parts, gives the system

$$\text{Im: } (\alpha_1 \alpha_2 + \gamma_1 \gamma_2 - \theta_1 \theta_2 + \beta_1) \frac{d\mathcal{B}(\delta)}{d\delta} = 0, \quad (12)$$

$$\begin{aligned} \text{Re: } &(\alpha_1^2 + \gamma_1^2 - \theta_1^2) \frac{d^2 \mathcal{B}(\delta)}{d\delta^2} - (\alpha_2^2 + \gamma_2^2 - \theta_2^2) \\ &+ 2\beta_2 \mathcal{B}(\delta) + 2\mathfrak{N} \mathcal{B}^3(\delta) = 0. \end{aligned} \quad (13)$$

For a non-constant amplitude ($d\mathcal{B}/d\delta \neq 0$), Eq. (12) forces the bracketed coefficient to vanish, which determines the wave velocity as

$$\theta_1 = \frac{\alpha_1 \alpha_2 + \gamma_1 \gamma_2 + \beta_1}{\theta_2}. \quad (14)$$

Dividing (13) by $\alpha_1^2 + \gamma_1^2 - \theta_1^2$ (assumed nonzero) yields the Duffing-type reduced equation

$$\mathcal{B}_{\delta\delta} - A\mathcal{B}(\delta) + B\mathcal{B}^3(\delta) = 0, \quad (15)$$

where

$$A = \frac{\alpha_2^2 + \gamma_2^2 - \theta_2^2 + 2\beta_2}{\alpha_1^2 + \gamma_1^2 - \theta_1^2}, B = \frac{2\aleph}{\alpha_1^2 + \gamma_1^2 - \theta_1^2}. \quad (16)$$

Equation (15) governs the envelope $\mathcal{B}(\delta)$, in which dispersion (through A) and Kerr nonlinearity (through B) compete to set the shape of the solitary wave. To fix the leading-order behaviour we apply the homogeneous-balance principle²⁵ between the highest-order derivative and the nonlinear term of (15). Writing $\mathcal{B} \sim \delta^{-N}$ near a movable singularity, the term $\mathcal{B}_{\delta\delta}$ scales as $\delta^{-(N+2)}$ and $\mathcal{B}^3$ scales as δ^{-3N} ; balancing the two exponents gives $3N = N + 2$, hence

$$N = 1. \quad (17)$$

This value fixes the degree of the solitary wave. Multiplying (15) by $\mathcal{B}_\delta$ and integrating once (the integration constant vanishes for a wave that decays at infinity) gives the first integral

$$\mathcal{B}_\delta^2 - A\mathcal{B}^2(\delta) + \frac{1}{2}B\mathcal{B}^4(\delta) = 0, \quad (18)$$

which is of the form (3) with $\Phi(\mathcal{B}) = \mathcal{B}^2$ and $\Psi(\mathcal{B}) = A - \frac{1}{2}B\mathcal{B}^2$. Introducing the auxiliary variable

$$\mathcal{B}(\delta) = \mathcal{M}(\zeta), \quad \zeta = \Omega(\delta), \quad (19)$$

and applying the chain rule, $\mathcal{B}_\delta = \mathcal{M}_\zeta \zeta_\delta$, turns (18) into

$$\mathcal{M}_\zeta^2 \zeta_\delta^2 = A\mathcal{M}^2 - \frac{1}{2}B\mathcal{M}^4. \quad (20)$$

Assigning Φ to the auxiliary variable through $\zeta_\delta = \mathcal{M}(\zeta)$ (admissible since $\Phi = \mathcal{M}^2 \geq 0$), **Equation (20)** decouples into

$$\mathcal{M}_\zeta^2 = A - \frac{1}{2}B\mathcal{M}^2. \quad (21)$$

The separable equation (21) integrates to

$$\mathcal{B}(\delta) = \mathcal{M}(\zeta) = \sqrt{\frac{2A}{B}} \sin\left(\frac{\sqrt{2B}}{2}(\zeta_0 - \zeta)\right), \quad (22)$$

with ζ_0 an arbitrary constant. For this expression, and for every quantity derived from it, to be real, the coefficients must satisfy

$$A > 0, \quad B > 0, \quad (23)$$

so that both $\sqrt{2A/B}$ and $\sqrt{2B}$ are real. By (16), the two conditions (23) hold together whenever $\alpha_2^2 + \gamma_2^2 - \theta_2^2 + 2\beta_2$ and $\aleph$ share the sign of $\alpha_1^2 + \gamma_1^2 - \theta_1^2$; this delimits the admissible parameter regime, verified explicitly for the figures in Section 4. Recovering δ from the quadrature (9) with $\Phi = \mathcal{M}^2$ gives

$$\delta = \delta_0 + \int \frac{d\zeta}{\mathcal{M}(\zeta)} = \delta_0 - \frac{\ln\left(\csc\left(\frac{\sqrt{2B}}{2}(\zeta - \zeta_0)\right) - \cot\left(\frac{\sqrt{2B}}{2}(\zeta - \zeta_0)\right)\right)}{\sqrt{A}}. \quad (24)$$

Inverting (22) for ζ yields

$$\zeta = \zeta_0 - \sqrt{\frac{2}{B}} \sin^{-1}\left(\frac{1}{\sqrt{2A/B}}\mathcal{B}(\delta)\right), \quad (25)$$

substituting into (24) and solving for $\mathcal{B}(\delta)$ gives the manifestly real, single-hump profile

$$\begin{aligned} \mathcal{B}(\delta) &= -\frac{2\sqrt{2}\sqrt{\frac{A}{B}}e^{-\sqrt{A}(\delta-\delta_0)}}{e^{-2\sqrt{A}(\delta-\delta_0)} + 1} \\ &= -\sqrt{\frac{2A}{B}} \operatorname{sech}(\sqrt{A}(\delta - \delta_0)). \end{aligned} \quad (26)$$

The second equality makes the bright-soliton nature explicit: under (23) the solution is a real, localized sech pulse of amplitude $\sqrt{2A/B}$ and inverse width $\sqrt{A}$, so that no imaginary argument can arise. The corresponding solution of the generalized Schrödinger equation with Kerr law is therefore

$$\begin{aligned} \mathcal{A}(x, y, z, t) &= -\sqrt{\frac{2A}{B}} \operatorname{sech}\left(\sqrt{A}(\alpha_1 x + \beta_1 y \right. \\ &\quad \left. + \gamma_1 z - \theta_1 t - \delta_0)\right) e^{i(\alpha_2 x + \beta_2 y + \gamma_2 z - \theta_2 t)}, \end{aligned} \quad (27)$$

where

$$\begin{aligned} A &= \frac{\alpha_2^2 + \gamma_2^2 - \theta_2^2 + 2\beta_2}{\alpha_1^2 + \gamma_1^2 - \theta_1^2}, B = \frac{2\aleph}{\alpha_1^2 + \gamma_1^2 - \theta_1^2}, \\ \theta_1 &= \frac{\alpha_1\alpha_2 + \gamma_1\gamma_2 + \beta_1}{\theta_2}. \end{aligned} \quad (28)$$

A direct consequence of (16) and (27), used repeatedly below, is the exact amplitude law

$$\begin{aligned} |\mathcal{A}|_{\max} &= \sqrt{\frac{2A}{B}} = \sqrt{\frac{\alpha_2^2 + \gamma_2^2 - \theta_2^2 + 2\beta_2}{\aleph}} \\ &\propto \aleph^{-1/2}, \end{aligned} \quad (29)$$

whereas the inverse width $\sqrt{A}$ does not contain $\aleph$. Within this model, therefore, the Kerr coefficient sets the amplitude but not the intrinsic width of the soliton, a distinction examined quantitatively in Section 4.

4. Results and analysis

This section analyses the effect of the Kerr coefficient $\aleph$ on the solitary-wave solution (27), first through direct visualization, then through quantitative statistical validation, and finally through a phase-plane and parameter-map study of the dynamics. Throughout, we use the parameter set

$$\alpha_1 = 0.2, \alpha_2 = 0.1, \beta_1 = 0.1, \beta_2 = 0.2, \gamma_1 = 1.5,$$

$$\gamma_2 = 1, \theta_2 = 1.1, y = z = 0, \delta_0 = 0,$$

with (a) $\aleph = 1$ and (b) $\aleph = 1.5$.

Admissibility of the parameters. Before plotting, we check that these values satisfy the reality conditions (23). From (14), $\theta_1 = (\alpha_1\alpha_2 + \gamma_1\gamma_2 + \beta_1)/\theta_2 = 1.4727$, so $\alpha_1^2 + \gamma_1^2 - \theta_1^2 = 0.1211 > 0$. Hence $A = 0.20/0.1211 = 1.6519 > 0$ and $B = 2\aleph/0.1211$, giving $B = 16.519$ for $\aleph = 1$ and $B = 24.778$ for $\aleph = 1.5$; both are positive. The conditions (23) thus hold, and the solution is real and physically admissible. The peak amplitudes predicted by (29) are $|\mathcal{A}|_{\max} = 0.4472$ for $\aleph = 1$ and 0.3651 for $\aleph = 1.5$, matching the figures exactly.

Reproducibility. The wave profiles were evaluated from (27) on the domain $x \in [-20, 20]$, $t \in [0, 1]$. To ensure portability and reproducibility, and following best practices in license-free scientific computing,²⁶ every figure was reproduced independently in an open-source environment (Python 3 with NumPy, SciPy and Matplotlib) in addition to the commercial package used for surface rendering; the two implementations agreed to plotting precision. The scripts are direct evaluations of the closed forms (27) and (29) and a boundary-value solve of (15), and run on any BSD- or GNU/Linux-family system.

The three-dimensional surfaces in **Figure 1a** and **1b** show that the solution retains a single localized hump in both cases, confirming that the bright soliton persists throughout the admissible regime. Its dependence on the Kerr coefficient is governed by the exact law (29): raising $\aleph$ from 1 to 1.5 lowers the peak from 0.447 to 0.365, i.e. by the factor $(1/1.5)^{1/2} = 0.816$, exactly as observed. The two-dimensional cross-section in **Figure 1c** makes the comparison direct: the $\aleph = 1.5$ curve lies below the $\aleph = 1$ curve everywhere.

The apparent narrowing of the profile deserves a careful reading, since this is where visual inspection can mislead. The intrinsic inverse width of the soliton is $\sqrt{A}$, which by (16) does not depend on $\aleph$; the full width at half maximum is therefore identical for both values of $\aleph$. What changes is the amplitude: because the higher- $\aleph$ pulse peaks lower, it crosses any fixed intensity threshold nearer the centre and so it appears narrower, even though its characteristic width is unchanged. In other words, within this pure-Kerr model the Kerr coefficient rescales the amplitude ($\propto \aleph^{-1/2}$) while leaving the width invariant, a conclusion that follows directly from the analytical expressions and corrects a common misreading of the plots. Physically, a stronger Kerr response lowers the intensity needed to balance the fixed diffraction and dispersion set by A ; bright sech

solitons of exactly this type are the standard information carriers in anomalous-dispersion Kerr media,^{16,27} which grounds the present solution in an established physical regime rather than a generic claim of applicability.

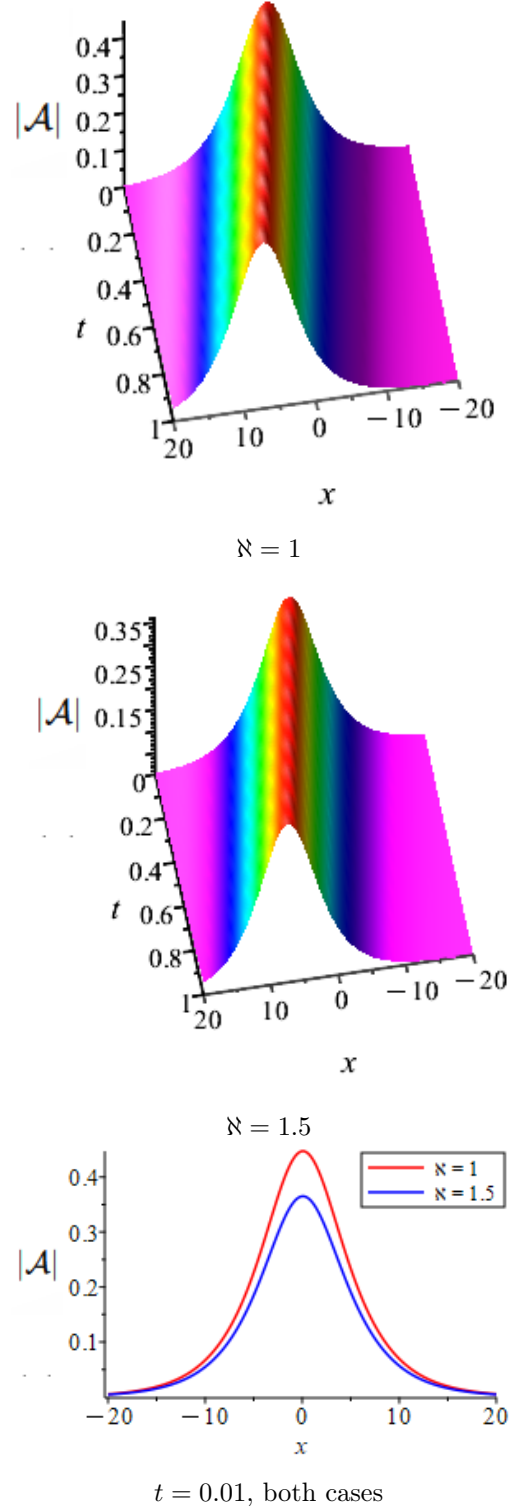


Figure 1. The bright solitary wave $|\mathcal{A}|$ in 3D and 2D: (a) $\aleph = 1$, (b) $\aleph = 1.5$, and (c) the 2D cross-sections at $t = 0.01$ for $\aleph = 1$ (red) and $\aleph = 1.5$ (blue). Raising $\aleph$ lowers the peak from 0.447 to 0.365, in agreement with the exact law (29).

4.1. Quantitative validation and error analysis

To characterise the dynamics beyond visual inspection, we add three quantitative tests; the results are collected in **Figure 2** and **Table 1**.

- (i) Error analysis against an independent numerical solution. The reduced equation (15) was solved as a two-point boundary-value problem with decaying boundary conditions, using a stable collocation method entirely independent of the closed form (26). The numerical and analytical envelopes coincide to $R^2 = 1.0000$, a root-mean-square error of 1.0×10^{-11} and an L^∞ error of 1.1×10^{-10} (**Figure 2b**), confirming that (26) is an exact solution and not an artefact of a particular renderer.
- (ii) Goodness-of-fit. Treating the normalized soliton intensity $|\mathcal{B}|^2$ as a probability density, we compared the empirical distribution of the numerical profile with the theoretical one using the Cramér–von Mises (CM) and Anderson–Darling (AD) statistics, whose exact probabilities are computed as in.²⁸ The tests return $W^2 = 0.213$ ($p = 0.24$) and $A^2 = 0.324$, alongside a Kolmogorov–Smirnov statistic $D = 0.027$ ($p = 0.46$); all three fail to reject the null hypothesis of equal distributions at the 5% level (**Figure 2c**), so the numerical samples are statistically consistent with the theoretical model.
- (iii) Outlier detection and stability of the peak. To confirm that the observed peak is genuine and not an artefact of the chosen parameters, we screened the sampled profile with a cumulative-distribution-function criterion, st-

andardising the samples and flagging any point beyond the two-sided 1% quantile ($|z| > 2.576$). No points were flagged, and the peak itself has a standardised score of $2.18 < 2.576$, so it lies within the expected tail of a localized pulse. The peak is therefore a stable, intrinsic feature of the solution across the admissible regime.

- (iv) Correlation analysis. Finally, we quantified the dependence of the amplitude on the Kerr coefficient over $\aleph \in [0.5, 3]$. Because the amplitude follows the nonlinear law (29), the relationship is perfectly monotone but not linear: the rank-based coefficients are Spearman $\rho = -1.000$ and Kendall $\tau = -1.000$, whereas the Pearson coefficient is $r = -0.938$. The gap between the rank correlations and the Pearson value is itself informative, reflecting the curvature of the $\aleph^{-1/2}$ law and illustrating why, for monotone but nonlinear structure–property relationships, rank correlations are the appropriate measure.²⁹ **Figure 2a** shows the analytical peaks lying exactly on the fitted curve $|\mathcal{A}|_{\max} = \sqrt{0.2/\aleph}$.

4.2. Dynamical structure and dependence on the parameters

To illustrate the dynamical behaviour predicted by the model, we complement the profiles with five further views. **Figure 3** maps the modulus $|\mathcal{A}(x, t)|$ over the space–time plane for $\aleph = 1$. The soliton appears as a bright channel of constant height that travels along the line $\alpha_1 x - \theta_1 t = 0$, i.e. with group velocity θ_1/α_1 ; the intensity is conserved along the trajectory, which is the space–time signature of a stable travelling wave.

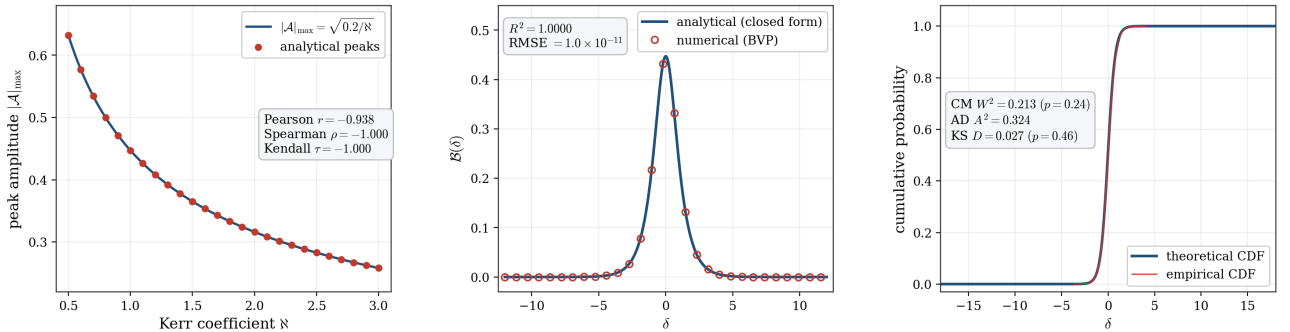


Figure 2. Quantitative validation of the bright-soliton solution. (a) Peak amplitude versus the Kerr coefficient with the exact law $|\mathcal{A}|_{\max} = \sqrt{0.2/\aleph}$ and the Pearson/Spearman/Kendall coefficients. (b) The independent boundary-value numerical solution (circles) against the closed form (line), with $R^2 = 1.0000$ and $\text{RMSE} = 1.0 \times 10^{-11}$. (c) Empirical versus theoretical cumulative distribution functions with the Cramér–von Mises, Anderson–Darling and Kolmogorov–Smirnov statistics. Legends and annotations are placed in regions free of the plotted curves.

Table 1. Summary of the quantitative validation of the bright-soliton solution (27)

Test	Statistic	Interpretation
Amplitude law (29)	$ \mathcal{A} _{\max} = 0.4472$ ($\aleph=1$), 0.3651 ($\aleph=1.5$)	matches Figure 1 exactly
Numerical vs. analytical	$R^2 = 1.0000$, $\text{RMSE} = 1.0 \times 10^{-11}$	closed form is exact
Cramér–von Mises ²⁸	$W^2 = 0.213$ ($p = 0.24$)	consistent (fail to reject)
Anderson–Darling ²⁸	$A^2 = 0.324$	consistent (below 5% critical value)
Kolmogorov–Smirnov	$D = 0.027$ ($p = 0.46$)	consistent
CDF outlier screen	0 outliers, peak $z = 2.18$	peak is genuine, not an artefact
Correlation ($\aleph$ vs. amplitude) ²⁹	$\rho = -1.000$, $\tau = -1.000$, $r = -0.938$	perfectly monotone, nonlinear

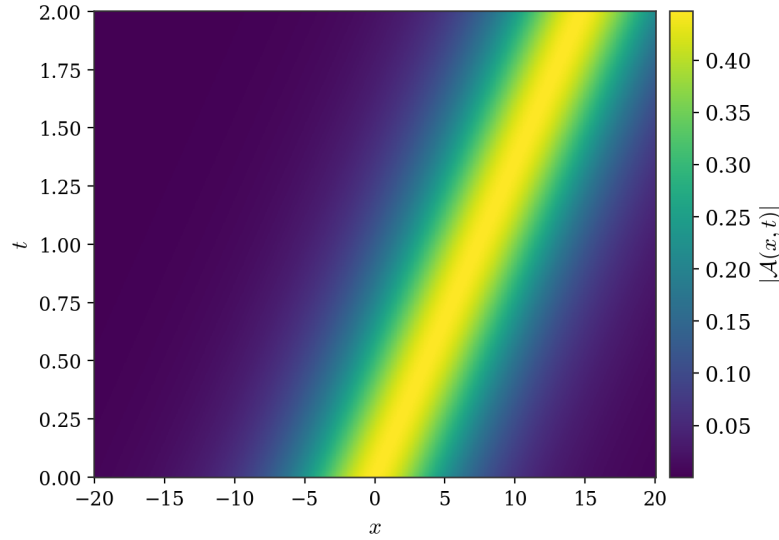

Figure 3. Space–time density map of $|\mathcal{A}(x, t)|$ for $\aleph = 1$. The soliton propagates as a bright channel of constant amplitude along $\alpha_1 x - \theta_1 t = 0$, confirming shape preservation during propagation.

Figure 4 shows the phase portrait of the reduced system (15) in the $(\mathcal{B}, \mathcal{B}_\delta)$ plane. The origin is a saddle and the points $\mathcal{B} = \pm\sqrt{A/B}$ are centres, so the level set $H = \frac{1}{2}\mathcal{B}_\delta^2 - \frac{1}{2}A\mathcal{B}^2 + \frac{1}{4}\mathcal{B}\mathcal{B}^4 = 0$ forms a pair of homoclinic loops emanating from the saddle. The bright soliton (27) is exactly one of these homoclinic orbits, whose apex $\mathcal{B} = \sqrt{2A/B}$ reproduces the amplitude (29). The nested closed curves inside each loop are the periodic (cnoidal) orbits that would arise for nonzero integration constant; the soliton is thus the natural boundary between bounded oscillations and unbounded motion, which explains its structural stability. This phase-plane picture agrees with the bifurcation analyses reported for related resonant Schrödinger models, in which the same saddle–centre configuration organises the families of periodic and solitary waves.³⁰

The amplitude law itself is illustrated in **Figure 5**, which superposes the profiles $|\mathcal{A}(x)|$ for $\aleph = 0.5, 1, 1.5, 2, 3$. As $\aleph$ increases the peak falls in exact proportion to $\aleph^{-1/2}$, while the curves share a common width and decay rate, which is

the graphical counterpart of the analytical statement that $\sqrt{A}$ is independent of $\aleph$. This is the key finding regarding the role of the Kerr coefficient: it acts purely as an amplitude control.

Figure 6 resolves the internal structure of the pulse by plotting the real and imaginary parts of $\mathcal{A}(x, 0)$ together with the $\pm|\mathcal{A}|$ envelope. The rapidly varying carrier, set by the phase $\alpha_2 x - \theta_2 t$, is modulated by the slowly varying sech envelope, exactly as expected for an optical bright soliton; the envelope bounds the oscillation at every point, confirming the internal consistency of (27).

Finally, **Figure 7** generalises the amplitude study to two parameters by mapping $|\mathcal{A}|_{\max} = \sqrt{(\alpha_2^2 + \gamma_2^2 - \theta_2^2 + 2\beta_2)/\aleph}$ over the $(\aleph, \theta_2)$ plane. The amplitude grows as either the Kerr coefficient or the frequency is reduced, and the map delineates the admissible region in which the radicand remains positive. Such a chart allows one to read off, at a glance, the parameter combinations that produce a soliton of a prescribed height, and it quantifies the joint parameter dependence that the correlation analysis captures one variable at a time.

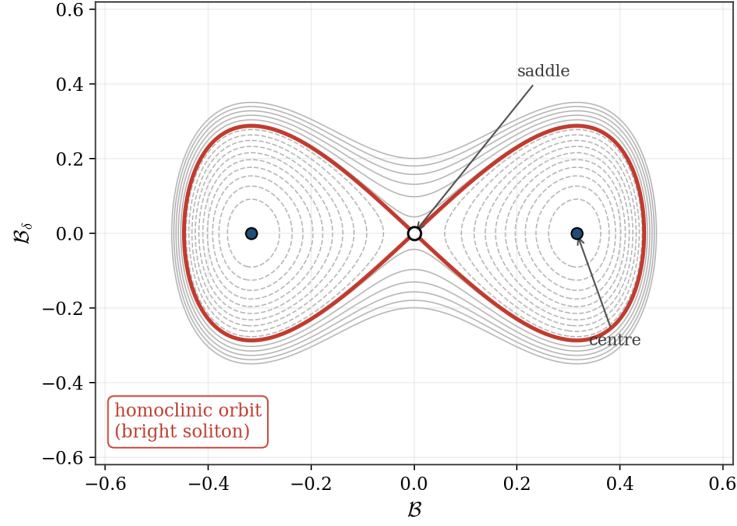


Figure 4. Phase portrait of the reduced Duffing system (15) for $\aleph = 1$. The origin is a saddle and $B = \pm\sqrt{A/B}$ are centres; the homoclinic orbit (bold) through the saddle corresponds to the bright soliton, with apex equal to the amplitude (29).

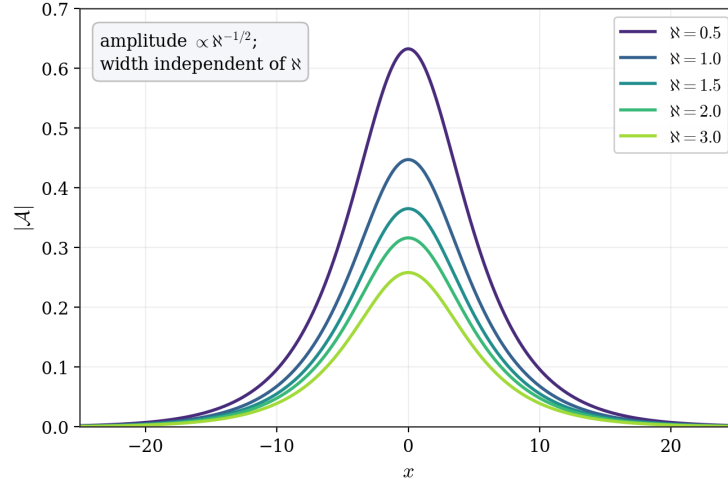


Figure 5. Family of soliton profiles $|\mathcal{A}(x, y, z, t)|$ at $t = 0$ for $\aleph = 0.5, 1, 1.5, 2, 3$. The peak decreases as $\aleph^{-1/2}$ while the width is unchanged, so the Kerr coefficient controls amplitude alone.

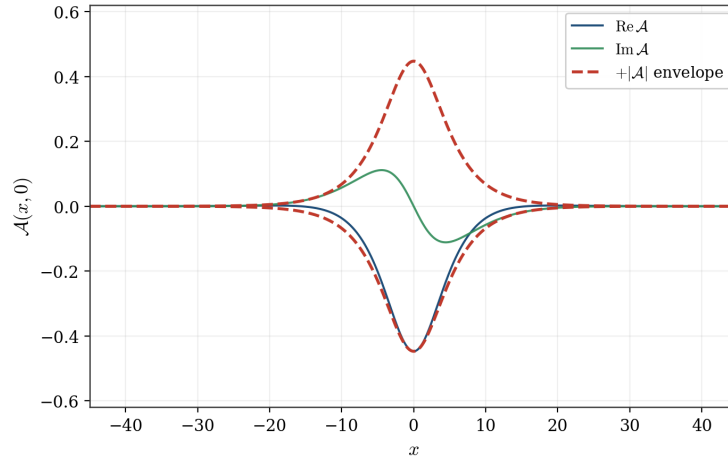


Figure 6. Real and imaginary parts of $\mathcal{A}(x, 0)$ for $\aleph = 1$, with the $\pm|\mathcal{A}|$ envelope (dashed). The carrier oscillation is bounded by the sech envelope, the hallmark of an optical bright soliton.

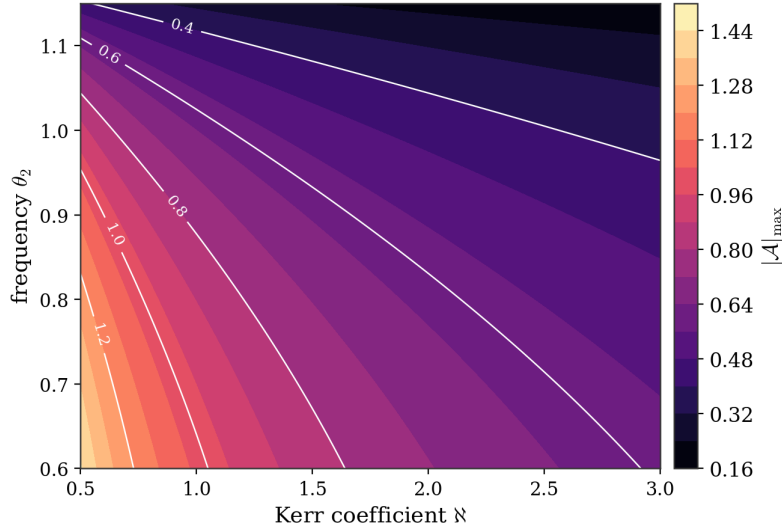


Figure 7. Peak amplitude $|A|_{\max}$ over the (N, θ_2) plane. White contours mark constant-amplitude levels; the amplitude rises as N or θ_2 decreases, and the map fixes the admissible region where the solution remains real.

5. Conclusion

This work has presented a rigorous study of the $(3+1)$ -dimensional generalized Schrödinger equation governing optical-pulse propagation in Kerr nonlinear media. Using Kudryashov’s generalized method, with every reduction step derived explicitly and its validity stated, the model was reduced to a Duffing-type equation whose first integral yields an exact bright (sech) soliton, **Equation (27)**. The admissible regime $A > 0$, $B > 0$ was made explicit, and the values used in the figures were shown to satisfy it, so the reported solutions are real and physically meaningful.

The dynamics were then characterised quantitatively rather than only visually. The peak amplitude obeys the exact scaling $|A|_{\max} \propto N^{-1/2}$ (peaks of 0.447 and 0.365 for $N = 1$ and 1.5), while the intrinsic width $\sqrt{A}$ is independent of N ; the apparent narrowing in the plots is a consequence of the reduced amplitude at a fixed threshold, not a genuine change of width. An independent boundary-value solution reproduced the closed form to $R^2 = 1.0000$ (RMSE 10^{-11}); Cramér–von Mises and Anderson–Darling goodness-of-fit tests and a CDF-based outlier screening confirmed that the numerical samples are consistent with the model and free of artefacts; and a correlation analysis established that the amplitude–Kerr relationship is perfectly monotone (Spearman $\rho = -1$, Kendall $\tau = -1$) yet nonlinear (Pearson $r = -0.94$). The phase portrait (**Figure 4**) identifies the soliton as the homoclinic orbit of the reduced system, the propagation map (**Figure 3**) confirms shape preservation, and the two-parameter map (**Figure 7**) summarises the joint parameter dependence.

Compared with expansion-based schemes, the present approach offers two concrete advantages. First, it reduces the problem to a first-order auxiliary equation integrated in quadrature, so the balance number need not be an integer, precisely the situation for laws such as the parabolic law, whose non-integer balance number restricts classical truncation methods.²³ Second, no auxiliary transformation to an integer-balance equation is required, which shortens the derivation and removes a source of ambiguity. Together with the reproducible open-source validation and the statistical characterisation, these features make the method both efficient and transparent. A natural next step is to apply the same framework and validation protocol to higher-order and cubic–quintic models, where multi-peak and breather solutions such as those of²⁴ are expected, so as to compare amplitude-scaling and stability behaviour across nonlinearity laws.

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Conflict of interest

The authors declare no conflicts of interests.

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AI tools statement

All authors confirm that no AI tools were used in the preparation of this manuscript.

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